



Introduction

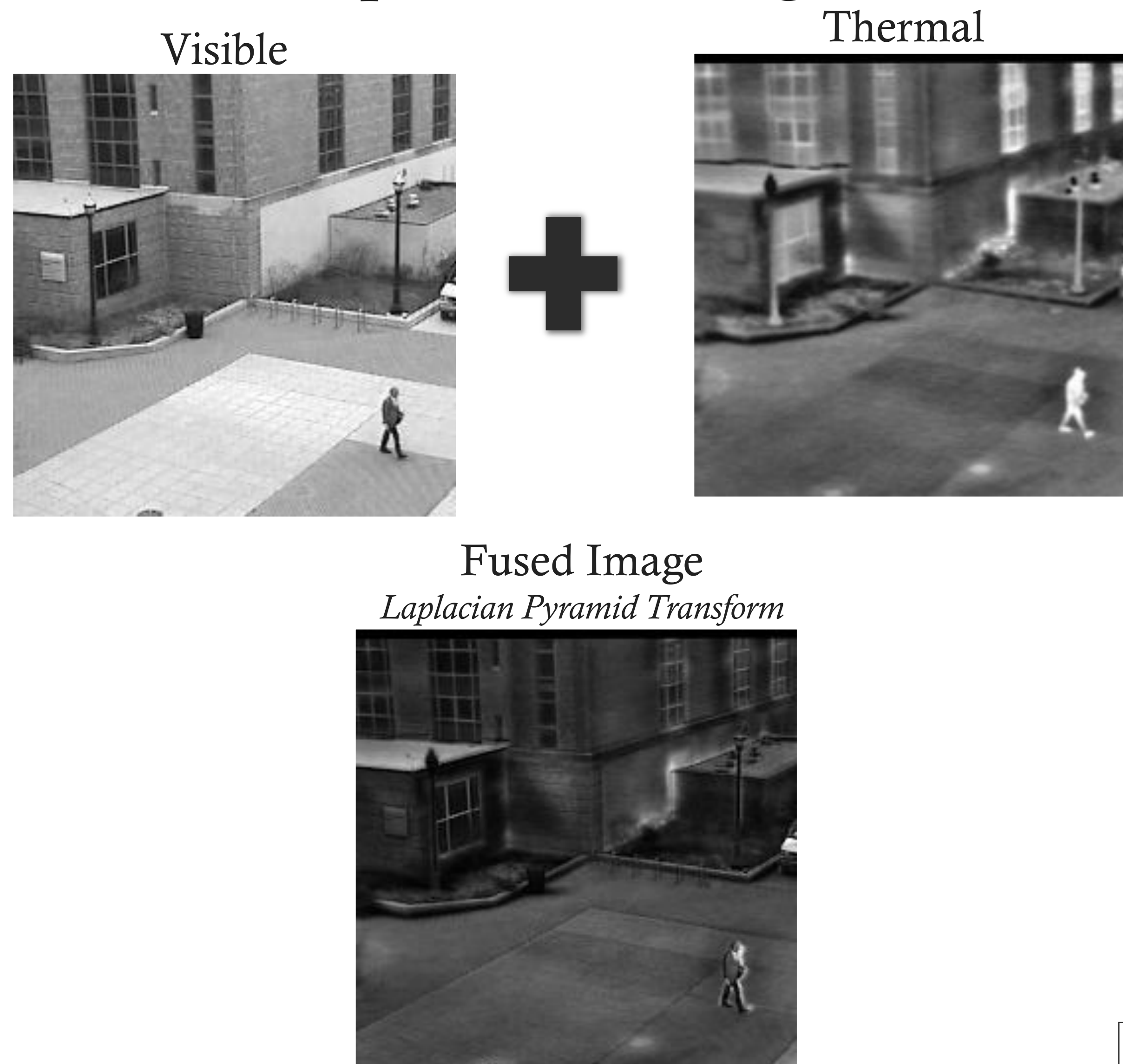
The additional information available from infrared sensors can aid in decision making when combined in visual information.

Despite the potential benefits of having multispectral information, recent research indicated limited capacity whether images were combined in a single image or presented side-by-side.⁴

Dynamic environments provide real-world stimuli with highly correlated movement of objects across time that may provide speed-ups in cognitive processes.

- We are interested in whether the results of processing strategies for static stimuli generalize to dynamic environments.

Experimental Design



Task: Is the person(s) walking toward the left or right side of the camera? Respond quickly and accurately (> 80%).

Multispectral Presentation Conditions (300ms) :

- Side-by-Side (SxS):** Display the two videos directly next to one another with no overlap.
- Algorithm (Alg):** Display a single, composite video that combines relevant information from each individual sensor video using the Laplacian pyramid transform.

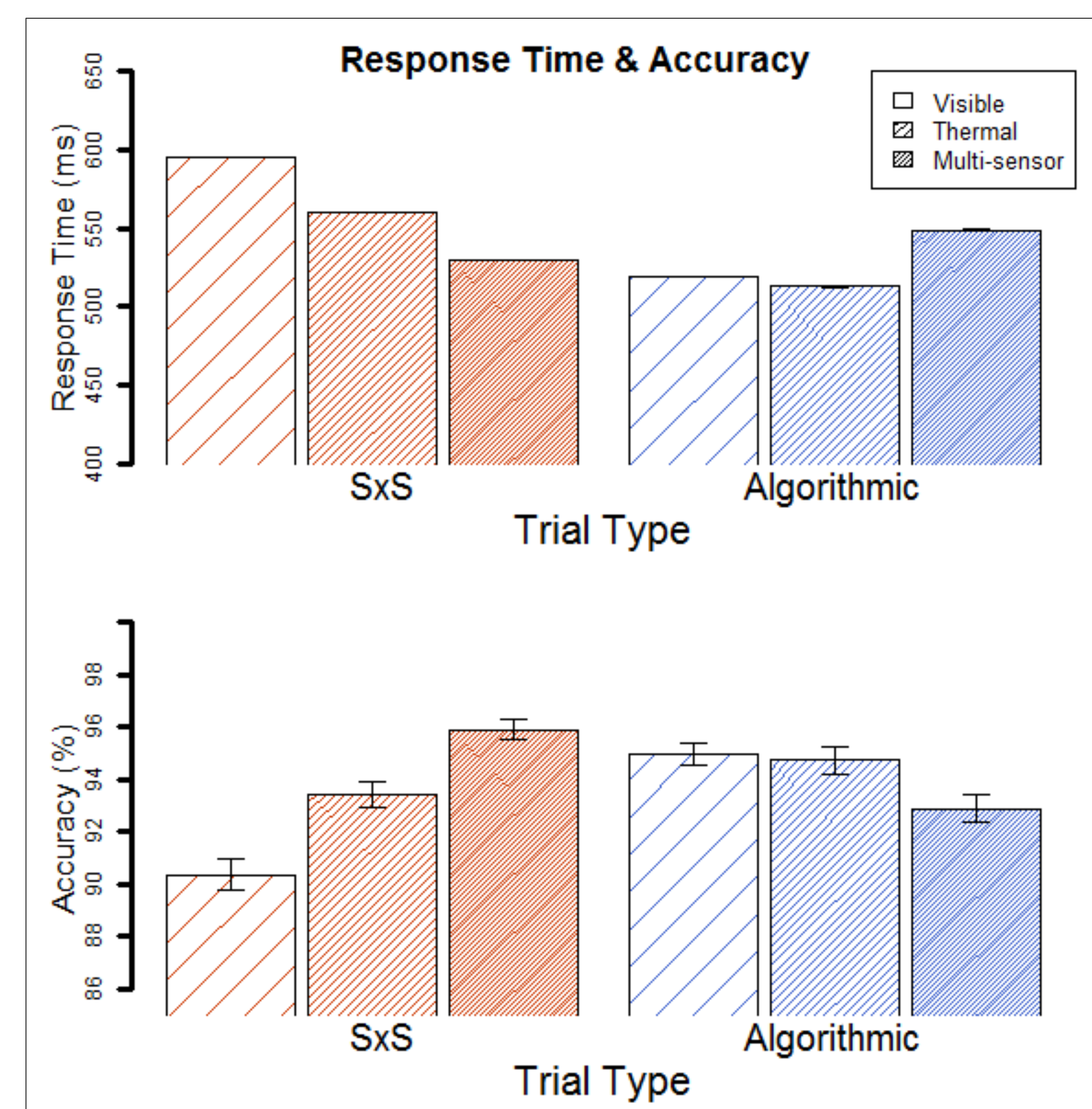
Model Comparisons

Capacity Coefficient^{6,7}:

$$C_{OR} = \frac{\hat{H}_{1..n}(t)}{\sum_{i=1}^n \hat{H}_i(t)} \begin{cases} C = 1: \text{Unlimited} \\ C < 1: \text{Limited} \\ C > 1: \text{Super} \end{cases}$$

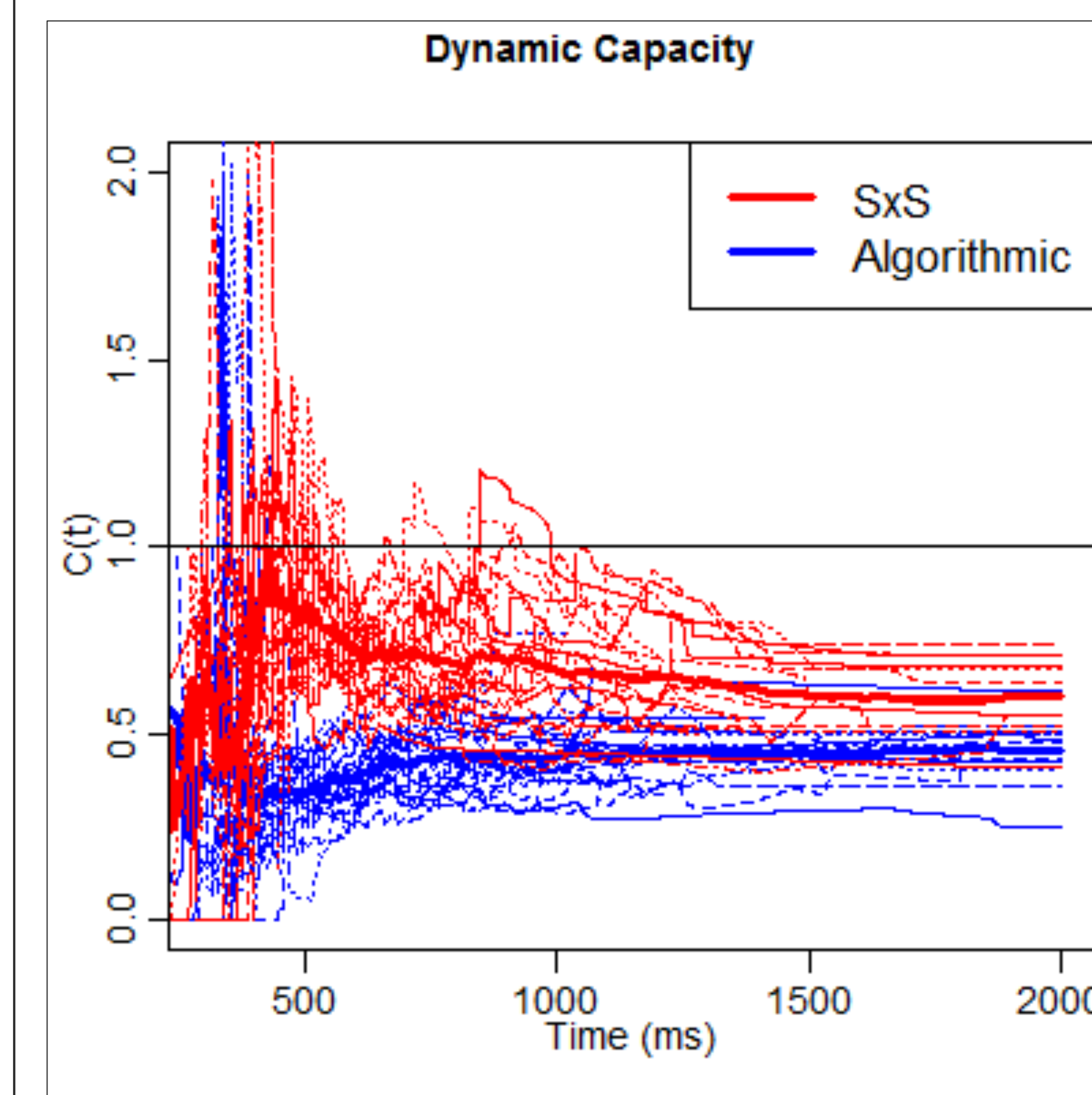
Results

Response Time and Accuracy



	df	Response Times		Accuracy	
		F	η	F	η
# of Sensors x Condition	1,21	178.25***	0.071	34.20***	0.101
# of Sensors (single, multiple)	1,21	7.96*	0.003	10.51***	0.014
Condition (Alg, SxS)	1,21	6.52*	0.020	0.00	0.000
Single-sensor presentation	1,21	39.38***	0.164	8.65***	0.121

Capacity Coefficient



Capacity z-score values significantly differ by presentation condition, $t(20) = 14.66, p < .05$.

z-score (range, M):

Side-by-Side:
-4.59 to -1.17 (M = -2.93)

Algorithmic:
-10.36 to -6.26 (M = -7.95)

Discussion

- Display of dynamic multispectral information shows less efficient processes than we would expect given the processing of each sensor alone.
- The redundancy of movement across various types of multispectral imagery displayed simultaneously may provide additional speed-ups that are not provided by a single, composite image.

Conclusions

- Response time and accuracy performance significantly varies based on the sensor and the multispectral presentation method.
- For these stimuli, all multispectral fusion methods result in limited workload capacity and capacity varies by condition.

Future Research

- Dynamic visual search⁵
- Response classification^{1,2,3}

References

- Ahumada, A. J. (2002). Classification image weights and internal noise level estimation. *Journal of Vision*, 2, 121-131.
- Ahumada, A. J., & Lovell, J. (1971). Stimulus features in signal detection. *Journal of the Acoustic Society of America*, 49, 1751-1756.
- Bittner, J. (2015). Areas of visual information utilized by humans in multispectral fused imagery using classification images. 56th Annual Meeting of the Psychonomics Society; Chicago, IL.
- Fox, E.L., Houpt, J.W. (2016). The perceptual processing of fused multispectral imagery. *Cognitive Research: Principles and Implications*, 1, 31.
- Glavan, J. J., Haggitt, J. M. & Houpt, J. W. (2017). Temporal organization of color and shape processing during visual search. Manuscript in preparation.
- Houpt, J. W., Blaha, L. M., McIntire, J. P., Havig, P. R., Townsend, J. T. (2013). Systems Factorial Technology with R. *Behavior Research Methods*. Advance online publication. doi: 10.3758/s13428-013-0377-3
- Houpt, J. W. & Townsend, J.T. (2012). Statistical measures for workload capacity analysis. *Journal of Mathematical Psychology*, 56, 341-355.

Acknowledgements: This work was supported by AFOSR Grant FA9550-13-1-0087.